

Programme/Class: <b>Certificate</b>		Year: <b>First</b>	Semester: <b>First</b>
Subject: <b>Physics</b>			
Course Code: <b>B010101T</b>		Course Title: <b>Mathematical Physics &amp; Newtonian Mechanics</b>	
<b>Course Outcomes (COs)</b>			
<ol style="list-style-type: none"> <li>1. Recognize the difference between scalars, vectors, pseudo-scalars and pseudo-vectors.</li> <li>2. Understand the physical interpretation of gradient, divergence and curl.</li> <li>3. Comprehend the difference and connection between Cartesian, spherical and cylindrical coordinate systems.</li> <li>4. Know the meaning of 4-vectors, Kronecker delta and Epsilon (Levi Civita) tensors.</li> <li>5. Study the origin of pseudo forces in rotating frame.</li> <li>6. Study the response of the classical systems to external forces and their elastic deformation.</li> <li>7. Understand the dynamics of planetary motion and the working of Global Positioning System (GPS).</li> <li>8. Comprehend the different features of Simple Harmonic Motion (SHM) and wave propagation.</li> </ol>			
Credits: <b>4</b>		Core Compulsory / Elective	
Max. Marks: <b>25+75</b>		Min. Passing Marks:	
Total No. of Lectures-Tutorials-Practical (in hours per week): L-T-P: <b>4-0-0</b>			
Unit	Topics		No. of Lectures
<b><u>PART A</u></b>			
<b>Basic Mathematical Physics</b>			
<b>I</b>	<p style="text-align: center;"><i>Introduction to Indian ancient Physics and contribution of Indian Physicists, in context with the holistic development of modern science and technology, should be included under Continuous Internal Evaluation (CIE).</i></p> <p style="text-align: center;"><b>Vector Algebra</b></p> <p>Coordinate rotation, reflection and inversion as the basis for defining scalars, vectors, pseudo-scalars and pseudo-vectors (include physical examples). Component form in 2D and 3D. Geometrical and physical interpretation of addition, subtraction, dot product, wedge product, cross product and triple product of vectors. Position, separation and displacement vectors.</p>		7
<b>II</b>	<p style="text-align: center;"><b>Vector Calculus</b></p> <p>Geometrical and physical interpretation of vector differentiation, Gradient, Divergence and Curl and their significance. Vector integration, Line, Surface (flux) and Volume integrals of vector fields. Gradient theorem, Gauss-divergence theorem, Stoke-curl theorem, Greens theorem and Helmholtz theorem (statement only). Introduction to Dirac delta function.</p>		8
<b>III</b>	<p style="text-align: center;"><b>Coordinate Systems</b></p> <p>2D &amp; 3D Cartesian, Spherical and Cylindrical coordinate systems, basis vectors, transformation equations. Expressions for displacement vector, arc length, area element, volume element, gradient, divergence and curl in different coordinate systems. Components of velocity and acceleration in different coordinate systems. Examples of non-inertial coordinate system and pseudo-acceleration.</p>		8

IV	<p style="text-align: center;"><b>Introduction to Tensors</b></p> <p>Principle of invariance of physical laws w.r.t. different coordinate systems as the basis for defining tensors. Coordinate transformations for general spaces of nD, contravariant, covariant &amp; mixed tensors and their ranks, 4-vectors. Index notation and summation convention. Symmetric and skew-symmetric tensors. Invariant tensors, Kronecker delta and Epsilon (Levi Civita) tensors. Examples of tensors in physics.</p>	7
<p><b><u>PART B</u></b></p> <p><b>Newtonian Mechanics &amp; Wave Motion</b></p>		
V	<p style="text-align: center;"><b>Dynamics of a System of Particles</b></p> <p>Review of historical development of mechanics up to Newton. Background, statement and critical analysis of Newton's axioms of motion. Dynamics of a system of particles, centre of mass motion, and conservation laws &amp; their deductions. Rotating frames of reference, general derivation of origin of pseudo forces (Euler, Coriolis &amp; centrifugal) in rotating frame, and effects of Coriolis force.</p>	8
VI	<p style="text-align: center;"><b>Dynamics of a Rigid Body</b></p> <p>Angular momentum, Torque, Rotational energy and the inertia tensor. Rotational inertia for simple bodies (ring, disk, rod, solid and hollow sphere, solid and hollow cylinder, rectangular lamina). The combined translational and rotational motion of a rigid body on horizontal and inclined planes. Elasticity, relations between elastic constants, bending of beam and torsion of cylinder.</p>	8
VII	<p style="text-align: center;"><b>Motion of Planets &amp; Satellites</b></p> <p>Two particle central force problem, reduced mass, relative and centre of mass motion. Newton's law of gravitation, gravitational field and gravitational potential. Kepler's laws of planetary motion and their deductions. Motions of geo-synchronous &amp; geo-stationary satellites and basic idea of Global Positioning System (GPS).</p>	7
VIII	<p style="text-align: center;"><b>Wave Motion</b></p> <p>Differential equation of simple harmonic motion and its solution, use of complex notation, damped and forced oscillations, Quality factor. Composition of simple harmonic motion, Lissajous figures. Differential equation of wave motion. Plane progressive waves in fluid media, reflection of waves and phase change, pressure and energy distribution. Principle of superposition of waves, stationary waves, phase and group velocity.</p>	7
<p><b>Suggested Readings</b></p>		
<p><b><u>PART A</u></b></p> <ol style="list-style-type: none"> <li>Murray Spiegel, Seymour Lipschutz, Dennis Spellman, "Schaum's Outline Series: Vector Analysis", McGraw Hill, 2017, 2e</li> <li>A.W. Joshi, "Matrices and Tensors in Physics", New Age International Private Limited, 1995, 3e</li> </ol> <p><b><u>PART B</u></b></p> <ol style="list-style-type: none"> <li>Charles Kittel, Walter D. Knight, Malvin A. Ruderman, Carl A. Helmholz, Burton J. Moyer, "Mechanics (In SI Units): Berkeley Physics Course Vol 1", McGraw Hill, 2017, 2e</li> <li>Richard P. Feynman, Robert B. Leighton, Matthew Sands, "The Feynman Lectures on Physics - Vol. 1", Pearson Education Limited, 2012</li> <li>Hugh D. Young and Roger A. Freedman, "Sears &amp; Zemansky's University Physics with Modern Physics", Pearson Education Limited, 2017, 14e</li> <li>D.S. Mathur, P.S. Hemne, "Mechanics", S. Chand Publishing, 1981, 3e</li> </ol> <p style="text-align: center;"><i>Books published in Hindi &amp; Other Reference / Text Books may be suggested / added to this list by individual Universities.</i></p>		

<b>Suggestive Digital Platforms / Web Links</b>
1. MIT Open Learning - Massachusetts Institute of Technology, <a href="https://openlearning.mit.edu/">https://openlearning.mit.edu/</a> 2. National Programme on Technology Enhanced Learning (NPTEL), <a href="https://www.youtube.com/user/nptelhrd">https://www.youtube.com/user/nptelhrd</a> 3. Uttar Pradesh Higher Education Digital Library, <a href="http://heecontent.upsdc.gov.in/SearchContent.aspx">http://heecontent.upsdc.gov.in/SearchContent.aspx</a> 4. Swayam Prabha - DTH Channel, <a href="https://www.swayamprabha.gov.in/index.php/program/current_he/8">https://www.swayamprabha.gov.in/index.php/program/current_he/8</a>
<b>Course Prerequisites</b>
Physics in 12 <sup>th</sup> / Mathematics in 12 <sup>th</sup>
<b>This course can be opted as an Elective by the students of following subjects</b>
Open to all
<b>Suggested Continuous Internal Evaluation (CIE) Methods</b>
20 marks for Test / Quiz / Assignment / Seminar 05 marks for Class Interaction
<b>Suggested Equivalent Online Courses</b>
1. Swayam - Government of India, <a href="https://swayam.gov.in/explorer?category=Physics">https://swayam.gov.in/explorer?category=Physics</a> 2. National Programme on Technology Enhanced Learning (NPTEL), <a href="https://nptel.ac.in/course.html">https://nptel.ac.in/course.html</a> 3. Coursera, <a href="https://www.coursera.org/browse/physical-science-and-engineering/physics-and-astronomy">https://www.coursera.org/browse/physical-science-and-engineering/physics-and-astronomy</a> 4. edX, <a href="https://www.edx.org/course/subject/physics">https://www.edx.org/course/subject/physics</a> 5. MIT Open Course Ware - Massachusetts Institute of Technology, <a href="https://ocw.mit.edu/courses/physics/">https://ocw.mit.edu/courses/physics/</a>
<b>Further Suggestions</b>
<ul style="list-style-type: none"> <li>• Other Digital Platforms / Web Links and Equivalent Online Courses may be suggested / added to the respective lists by individual Universities.</li> <li>• <b>In End-Semester University Examinations, equal weightage should be given to Part A (units I to IV) and Part B (units V to VIII) while framing the questions.</b></li> </ul>